





LEVITATION

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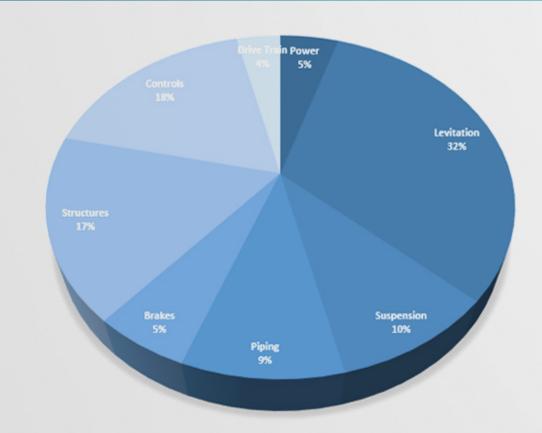
## **GOALS**

- To win first place at the SpaceX Hyper-loop Pod Competition in both overall point total and speed.
- To accelerate the development of a fast, economical, and sustainable transportation system.

# OBJECTIVES

- Design and build a 1:2 scale Hyperloop pod that utilizes air based levitation and is optimized for a 1 mile test track.
- Educate and train students in simulation and advanced manufacturing
- Collaborate with industry partners and students from many disciplines

# BUDGET BREAKDOWN



POD COST: \$53,306

Power

Structures

Suspension Piping

Brakes Controls

Levitation **Drive Train** 

## POWER

The power system consists two compressed air tanks, one auxiliary tank, and two rechargeable battery packs.

# CONTROLS

The control system manipulates actuators and valves to control the velocity,

lateral stability and levitation of the pod.

# **SUSPENSION**

Air bearings are surrounded by skirts to maintain a constant height of 2.5mm above the surface.

This system, containing one air spring and four metal springs, is designed to have two capabilities: vibration dampening and semi-instantaneous retraction.

### STRUCTURES

The structure of the frame is designed to include a strong inner core from which carbon sandwich plates and aluminum are extended to support the other systems.

# TEAM PHOTO



### TEAM MEMBERS

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