

GOALS

- To win first place at the SpaceX Hyperloop Pod Competition in both overall point total and speed.
- To accelerate the development of a fast, economical, and sustainable transportation system.

OBJECTIVES

- Design and build a 1:2 scale Hyperloop pod that utilizes air based levitation and is optimized for a one mile test track.
- Educate and train students in simulation and advanced manufacturing.
- Collaborate with industry partners and students from many disciplines.



Mile long Hyperloop tube at SpaceX headquarters in Hawthorne, CA

TOTAL POD COST





LEVITATION

The air based levitation system consists of four skis, each with a flexible bottom skirt and a carbon fiber top ski, that allow the pod to levitate on a cushion of air 2.5mm above the surface of the track.



TIMELINE

Design Weekend Jan., 2015

DESIGN

Arwa Tizani (atizani@uci.edu) Mackenzie Puig-Hall (mpuighal @uci.edu)

HYPERXITE Changing the Future of Transportation

STRUCTURES

The structure of the frame is designed to include a strong inner core from which carbon sandwich plates and aluminum are extended to support other systems.

POWER

The power system consists of two compressed air tanks, one auxiliary tank, and two rechargeable battery packs.

MAGNETIC BRAKING

The brakes use non-contact permanent magnets to induce eddy-currents in the aluminum rail. If there is a loss in power or air pressure, the brakes will engage.

CONTROLS

The controls system manipulates actuators and valves to control the velocity, lateral stability and levitation of the pod.

Elon Musk with the HyperXite pod at Competition Weekend

> The HyperXite team with our pod on the external subtract at Competition Weekend



On-Site Test Nov. 2-3, 2016

BUILD

Competition Weekend I Jan. 29-30, 2017

RE-DESIGN

BUILD

Competition Weekend II Summer 2017



ΤΕΑΜ ΡΗΟΤΟ



TEAM MEMBERS

Adith Narayan Shankar
Ana Dominguez
Arash Asgarinejad Anthony Long Arjuna Ravisha Rathnayake Mudiyanse Arwa Tizani Bander Linjawi
Brian O'Sullivan
Charleston Tran
Chris Lan Christian Aboga-a Clayton Younkers Colton Christiansen Devin Pozas
Jasmine Cordero Jason Kwon Kamran Sadaghiani Kevin Gonzalez
Khaled Takwa
Leslie Hsiao
Mackenzie Puig-Hall Maddy Sando 🔳 Maral Abbasinik 🔳 Mossab Khalid A Alsaedi 🔳 Nathan Sharifrazi Navpreet Singh Plaha Nick Parks Patricio Guerrero Patrick Chung Peter Sutliff Robert Chavez Steve Cho Takahiro Ishikawa 🛛 Wesley Hsiao 🗨 William Conner Farrell Woo Yoong Chong Zachary Rawlings

TEAM ORGANIZATION



Primary Advisor: Roger Rangel Advisors: Jack Brouwer, Kenneth Mease, Mahshid Fardadi, Khalid Rafique,Lorenzo Valdevit, Farzin Zareian, Manuel Gamero, Daniel Mumm, James Bobrow

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