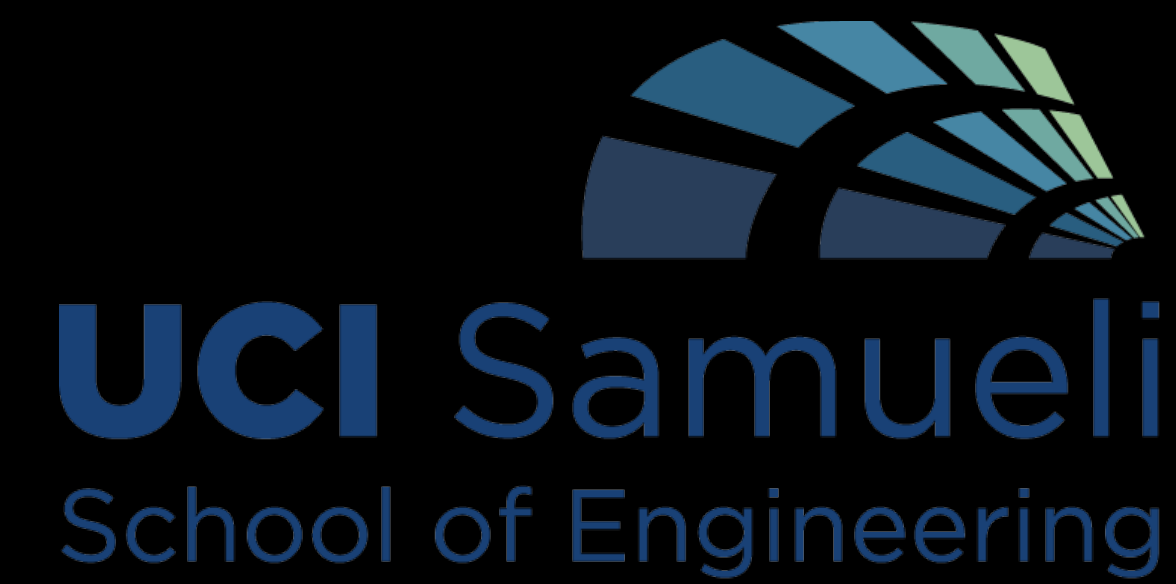


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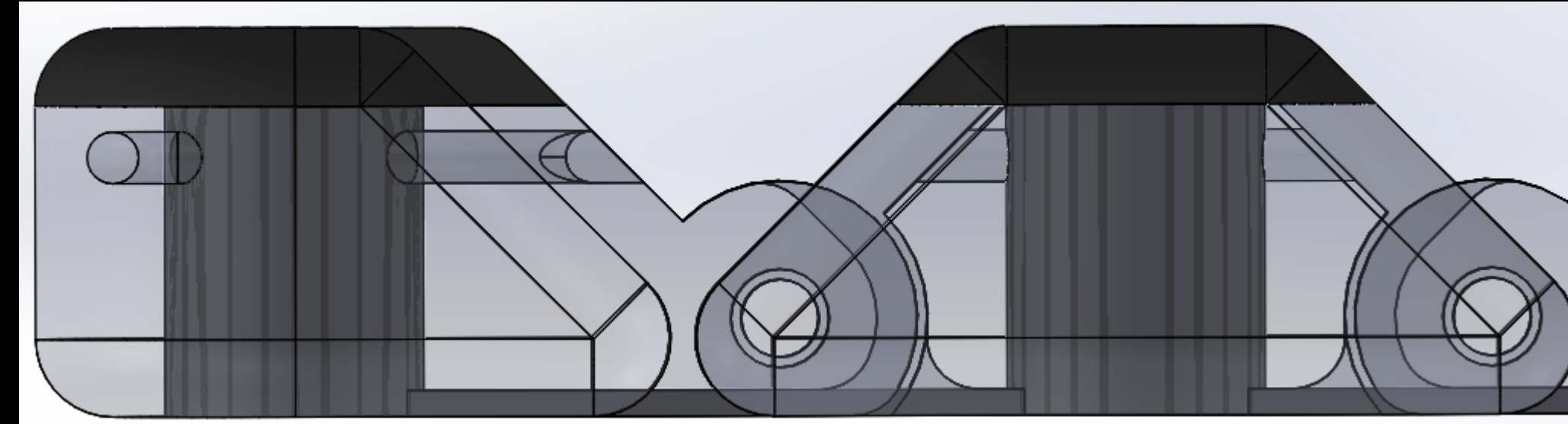
Krobohand

A 3D Printed, Robotic Prosthetic Hand



Background

The Krobohand group recognized a significant gap in the upper limb prosthetic industry between cost and functionality of a prosthetic.



← Joint Detail
- Side profile showing flexible tendon, grips, and core.

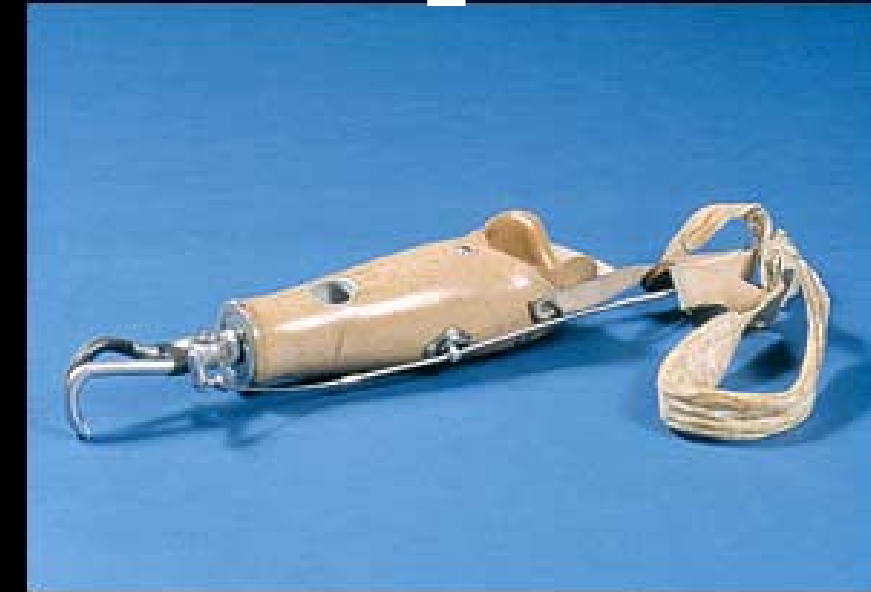
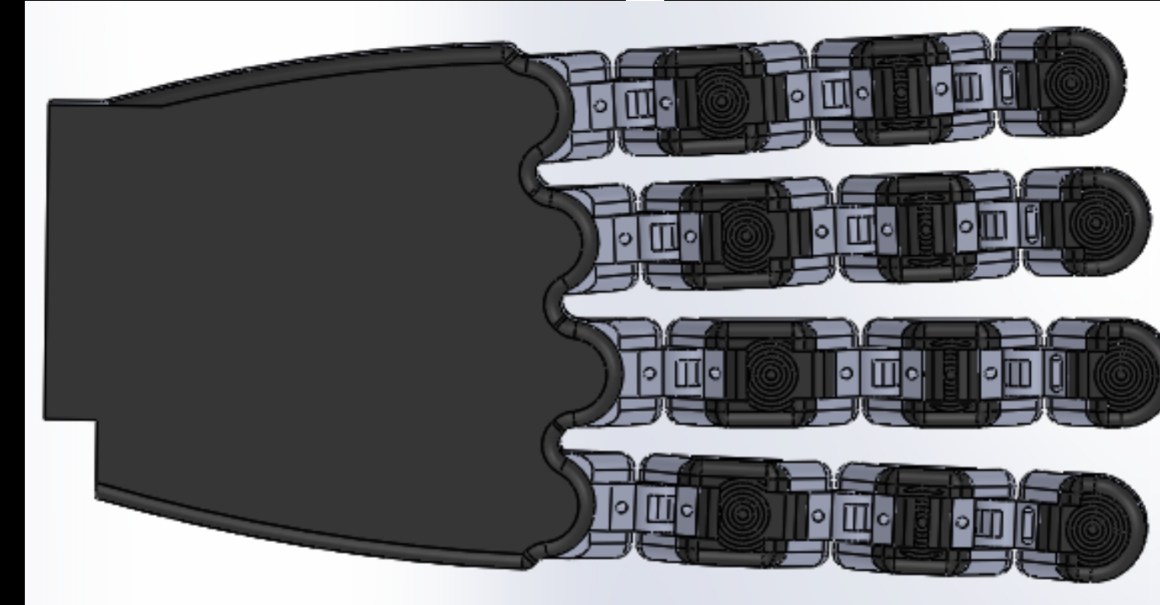
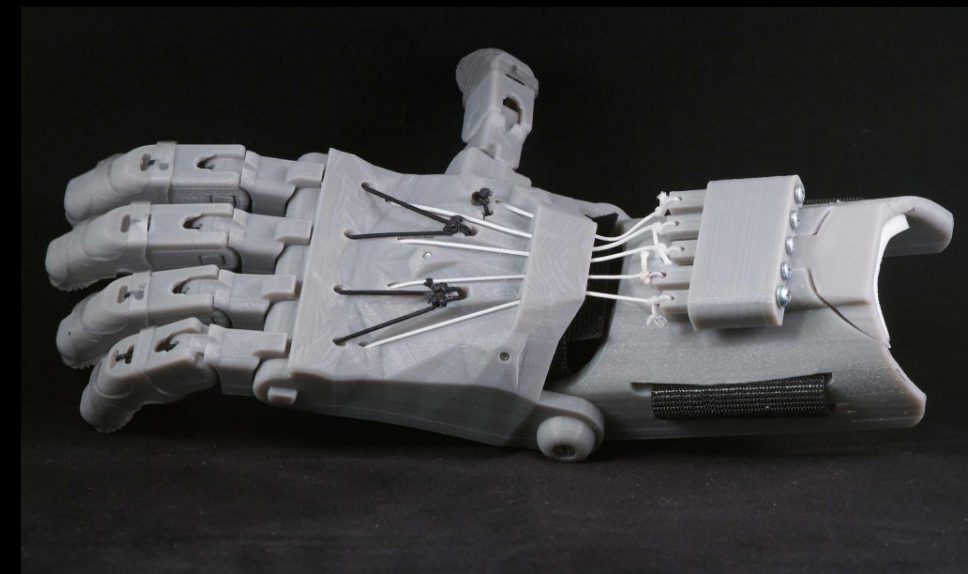
Design

Krobohand is both cost effective, as well as functionally viable. Fabrication techniques, as well as unique designs yield an innovative upper limb prosthetic.

Raptor Hand - \$50

Krobohand - < \$1000

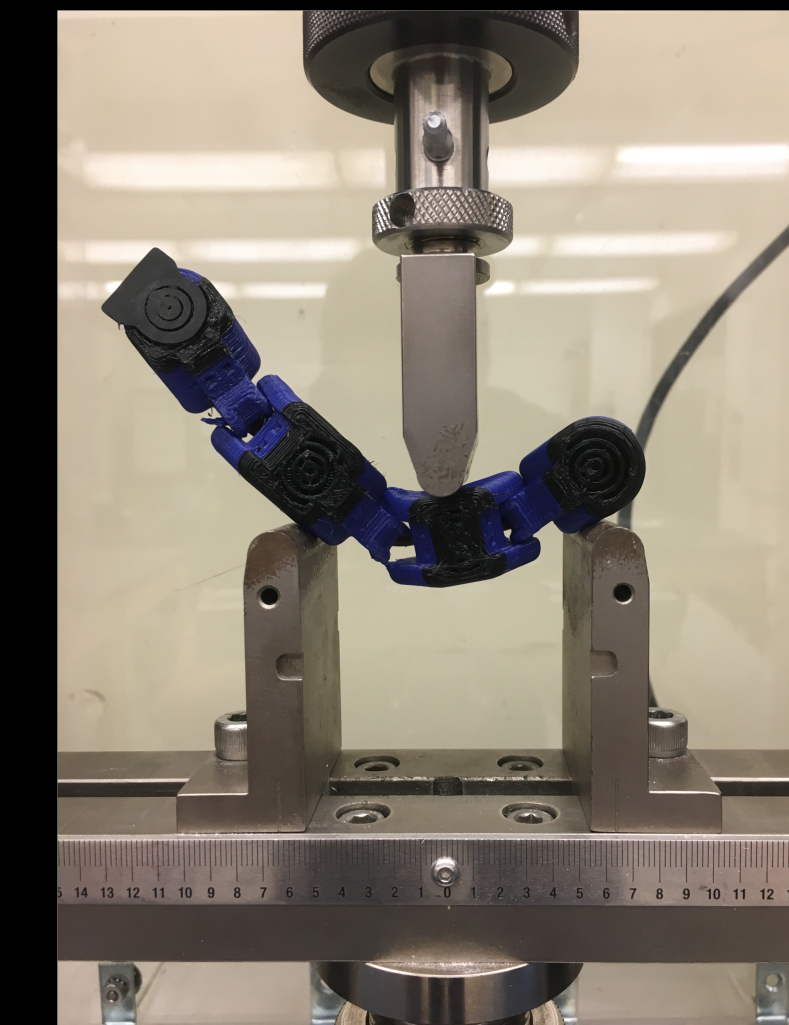
Split Hook - \$10,000



Tensile Test



3-Point Flexural Test



Innovation

- 1.) Fully 3D Printed Joints, Lateral Joints.
- 2.) Flexible tendon as a stabilizing, restoring force, like the extensor tendon of a human.
- 3.) Grip on palm side printed from same material as the flexible tendon, finger pads.
- 4.) Electromyography for connection between prosthesis and amputee, to be non-invasive.

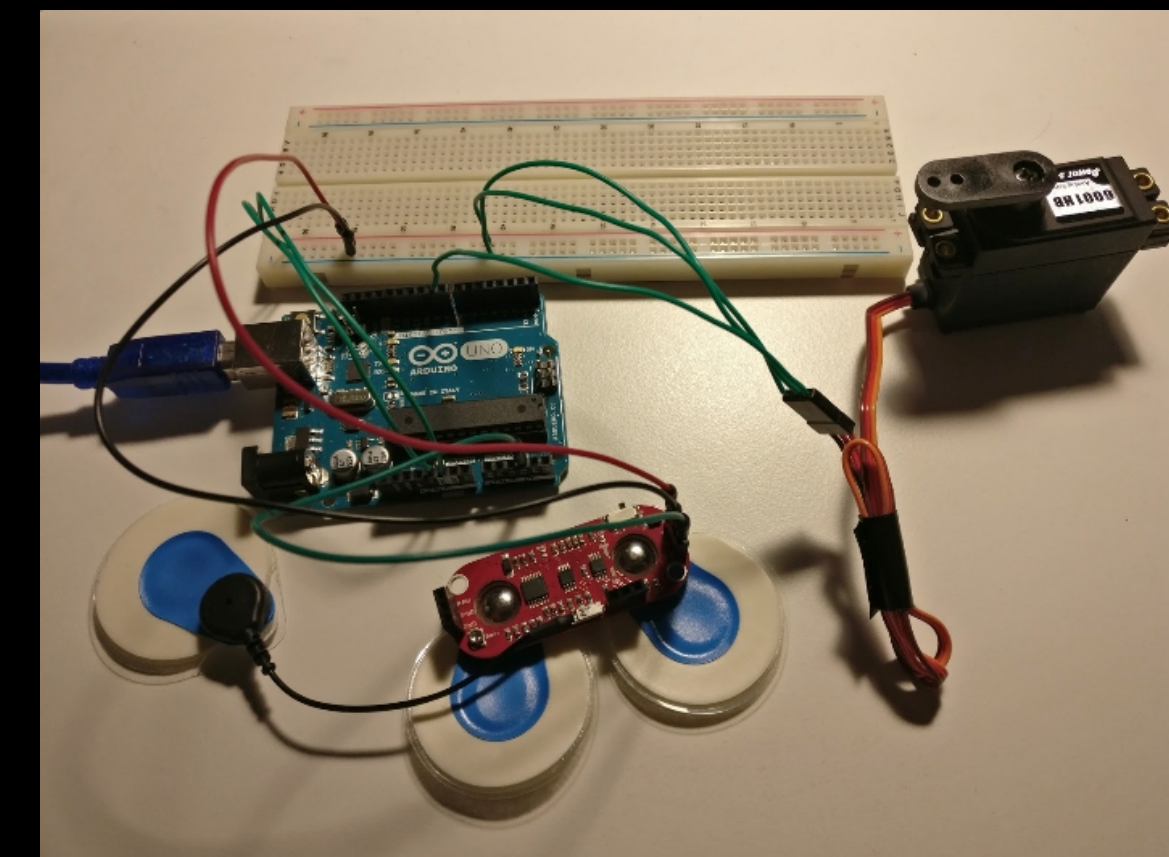
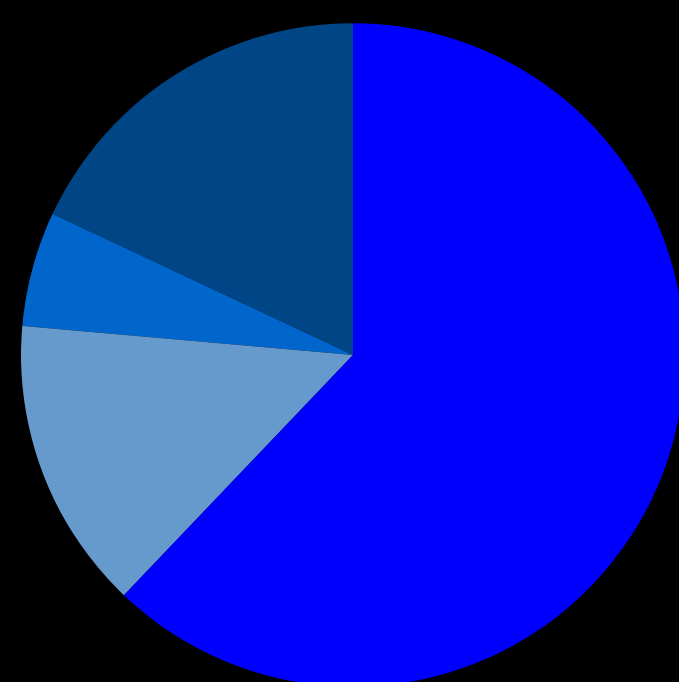
Goal

Bridge the gap in the upper limb prosthesis industry between cost and functionality.

Objectives

- 1.) Fabrication with dual material 3D Printing.
- 2.) Streamline process of connectivity between electromyographic sensors and amputee.
- 3.) Create a sleek, clean, and recognizable upper limb prosthesis.

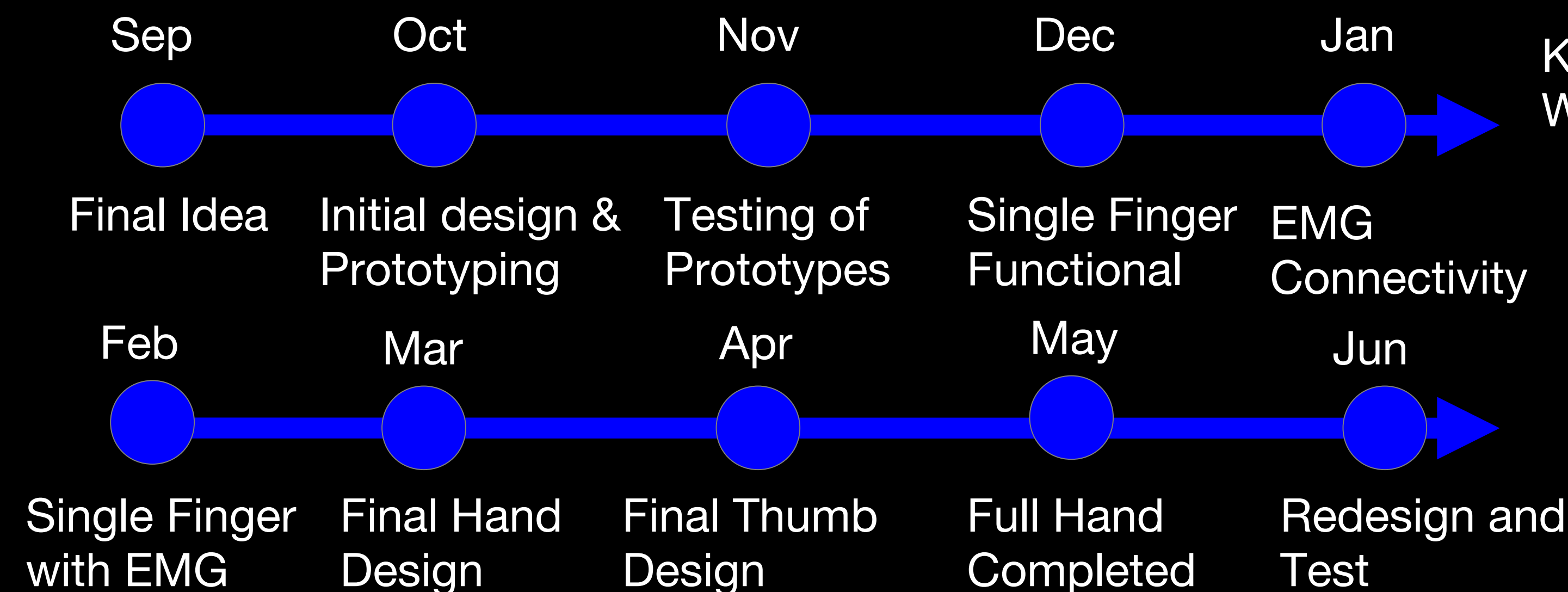
Budget: < \$1000 Total Cost



Electromyography

- 1.) MyoWare sensor connected to existing muscle groups.
- 2.) Signal interpreted by Arduino microcontroller (Uno or Mega), actuates motor.

Timeline: 2016-2017



Krobohand Workstation



The Team

- Ethan Kirkley
- Zepoor Khechadorian
- Advisor: Dr. Reinkensmeyer
- Cameron Hunt
- Kevin Wong